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# Effect of forest landscapes composition and configuration on bird community and its functional traits in a hotspot of biodiversity of Chile

Fulgencio Lisón <sup>1,2,\*</sup>, Camilo Matus-Olivares<sup>1,2,3</sup>, Ernesto Troncoso<sup>4</sup>, German Catalán<sup>2,3</sup>, María
 V. Jiménez-Franco<sup>5</sup>

<sup>1</sup>Wildlife Ecology and Conservation Lab, Departamento de Zoología, Facultad de Ciencias
 Naturales y Oceanográficas, Universidad de Concepción, Casilla 160-C, Concepción, Chile.
 <sup>2</sup>Laboratorio de Ecología del Paisaje y Conservación, Departamento de Ciencias Forestales y
 Medioambiente, Facultad de Ciencias Agropecuarias y Forestales, Universidad de La Frontera,
 Box 54-D, Temuco, Chile. Phone: +56 964 352 456/Fax: 56-41-2204709.

<sup>3</sup>Doctorado en Ciencias Agroalimentarias y Medioambiente, Facultad de Ciencias Agropecuarias
y Forestales, Universidad de La Frontera, Temuco, Chile.

<sup>4</sup>Magister en Recursos Naturales, Facultad de Ciencias Agropecuarias y Forestales, Universidad
de La Frontera, Temuco, Chile.

<sup>5</sup>Área de Ecología, Departamento de Biología Aplicada, Universidad Miguel Hernández, Avda.
Universidad, s/n. Edf. Vinalopó, 03202 Elche, Alicante.

e-mail addresses: Fulgencio Lisón (<u>flison@udec.cl</u>. ORCID: 0000-0003-1481-3750); Camilo
Matus-Olivares (<u>camilo.matus@ufrontera.cl</u>. ORCID: 0000-0002-2436-8374); Ernesto
Troncoso (<u>e.troncoso02@ufromail.cl</u>.); German Catalan (<u>german.catalan@ufrontera.cl</u>. ORCID:
0000-0002-9903-7481); María Victoria Jiménez-Franco (<u>maria.jimenezf@umh.es</u>. ORCID:
0000-0002-7254-0431)

\*Corresponding author: Fulgencio Lisón, Wildlife Ecology and Conservation Lab,
Departamento de Zoología, Facultad de Ciencias Naturales y Oceanográficas, Universidad de
Concepción, Casilla 160-C, Concepción, Chile. Phone: +56 964 352 456/Fax: 56-41-2204709.
E-mail: flison@udec.cl.

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29 Abstract

Understanding the effect of landscape configuration on the bird species richness and their 30 functional traits (dietary preferences) is important to link the conservation and restoration plans 31 to the production of the crops. Our aims were: 1) to study the influence of forest types (native, 32 mixed and plantations) on the bird species richness in two agroforestry landscapes 33 34 (heterogeneous/homogeneous); 2) to assess the effect of size/density of forest patches in the birds' functional traits; 3) to evaluate the effect of isolated trees on them, and 4) to discuss 35 conservation and restoration measures for the birds' functional traits in agroforestry landscapes. 36 37 We used hierarchical occupancy models to evaluate the effect of different landscape metrics and detectability measures on bird communities. We recorded a total of 64 bird species. The 38 estimated species richness was considerable higher in homogeneous landscape  $(31.7 \pm 2.7)$  than 39 heterogeneous (27.3  $\pm$  2.5). Our results showed the bird assemblage had a positive trend with 40 native forests, negative with mixed forests and neutral trend for plantations. The granivores and 41 insectivore's species showed significant preferences for homogeneous landscape, while 42 omnivores had significant preferences for heterogeneous landscape. Carnivores/Piscivores and 43 44 herbivores/frugivores species did not show preferences by any landscape type. The response of functional traits depended on different forests attributes. The isolated trees had a significant 45 effect on the birds' functional traits. In conclusion, it is necessary a deep knowledge about the 46 relationship between the landscape configuration and the bird species richness/functional traits. 47 These findings could help in the future with the conservation, restoration, and rewilding policies 48 in this important hotspot of biodiversity, avoiding alterations in the ecosystem services. 49

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Keywords: Agroforestry; Bird guilds; Landscape metrics; Occupancy models; Plantations.

# Introduction

The composition (land-use percentage) and disposition of elements that belong to the 53 agroforestry landscapes have serious implications in the distribution of the species and their 54 richness (Amos et al., 2013). The fragmentation of forest areas as a result of the land-use changes 55 has modified the configuration of the elements permanently, and consequently the wildlife must 56 57 adapt to the new situation. However, this usually supposes a declination or loss in their populations (Batáry et al., 2020; Carvajal et al., 2018; Daskalova et al., 2020; Docherty et al., 58 2020; García-Navas et al., 2020; Santos et al., 2021; Traba & Morales, 2019). The fragmentation 59 60 process is not uniform and can create different structures within the landscape configuration such as isolated trees, tree lines, corridors, large and homogeneous patches, smaller patches, etc. 61 (Altamirano et al., 2020; Daskalova et al., 2020; Martin et al., 2020; Valente & Betts, 2019). 62 This way, understanding how the distribution and location of these elements affect wildlife 63 (richness and functional traits) will help in the land-sharing/sparing debate (Arroyo-Rodríguez 64 et al., 2020; Brambilla, 2019; Cannon et al., 2019; Finch et al., 2019; Gilroy et al., 2014; Lamb 65 et al., 2019), as well as to design wildlife friendly areas in a global rewilding context (Kirk et al., 66 67 2020; Perino et al., 2019).

This landscape configuration can increase the mobility between different habitats (Väli 68 et al., 2020; Whytock et al., 2018), and therefore, it promotes the presence of many species with 69 different functions (Gardiner et al., 2019). The functional traits can affect significantly some of 70 the ecosystem services provided by animals in agroecosystems such as seed dispersion, 71 pollination, pest suppression (Arroyo-Rodríguez et al., 2020; Barros et al., 2019; Benedetti et al., 72 73 2020; Klingbeil & Willig, 2016). Therefore, it is necessary to understand the relationship between landscape elements and functional traits, because it is the keystone to develop 74 conservation and restoration plans (Benedetti et al., 2020; Dekeukeleire et al., 2019; Harris et 75 76 al., 2020).

77 Birds have many functions within the ecosystems (Barbaro et al. 2017; Redlich et al. 2018; Acosta-Rojas et al. 2019; Benedetti et al. 2020; Muñoz-Sáez et al. 2020), but currently 78 there is a strong decline in some of their populations (Bowler et al., 2019). Nevertheless, several 79 80 studies showed that the landscape configuration affected the presence/absence of the species and/or communities (Barros et al., 2019; Donald et al., 2019; Halstead et al., 2019; Ibarra & 81 Martin, 2015; Morante-Filho et al., 2020; Neilan et al., 2019). The absence of some elements 82 such as isolated trees or tree lines can disrupt the mobility of these species, and consequently 83 some suitable patches are not available for these species because they cannot get access to them 84 (Akresh et al., 2021). Also, these same elements avoid the species being perceptible for their 85 natural predators. On the other hand, the forest patches with different typologies and/or 86 vegetation communities are essential for birds, since they provide roosts, breeding places, prey, 87 88 etc. (Jiménez-Franco et al., 2018). Indeed, roads can increase noise contamination and affect the presence of some species (Cooke et al., 2020; Hall et al., 2016; Sol et al., 2020). 89

90 La Araucania region is placed in the centre-south of Chile and is part of a biodiversity hotspot (Fuentes-Castillo et al., 2020; Myers et al., 2000). However, in the last decades, the 91 92 central valley has suffered large changes in landscape composition based on anthropogenic 93 transformations with a great loss of native forests, where a significate proportion (21% between 1970-1990; 17% between 1990-2000; and 22% between 2000-2010) of native forest became in 94 other land uses (forest plantations of non-native species, shrublands, agriculture and pasture; 95 96 Miranda et al. 2015, 2017). Also, the presence of fires is high, especially due to human activity (Miranda et al., 2020). However, this transformation is not uniform and we can basically find 97 two types of landscape: heterogeneous landscapes with small patches of crops which are 98 interconnected. and homogeneous, based on areas with large crop extensions (see Figure 1). 99

Our hypothesis was that species richness and functional traits of the bird community willbe higher in those landscapes with a heterogeneous configuration and with a high availability of

102 landscape elements such as native forest (Atauri & de Lucio, 2001). This way, the aims of this 103 study were: 1) to study and assess the influence of forest patches types on the bird species 104 richness and their functional traits in both landscape types (homogeneous vs. heterogeneous); 2) 105 to evaluate the effect of isolated trees on birds' functional traits; and 3) to discuss conservation 106 and restoration measures for functional bird diversity in agroforestry landscapes. We hope that 107 this study helps wildlife managers to understand landscape composition and configuration in 108 relation to species richness in order to conserve important hotspot of biodiversity.

109 Material and Methods

#### 110 *Study area*

The study area is located in the central valley of La Araucania region in the centre-south of 111 112 Chile (mid-coordinates are 38°51'S latitude, 72°20'W longitude; Figure 1). The valley is 113 dominated by alluvial plains where the native forest has disappeared in favour of intensive crops, urban areas and forest plantations (Miranda et al., 2015, 2017). Today, most of the land cover 114 (ca.75%) in the Araucania Central Valley is crop and pasture land, with a recent increase in 115 116 exotic tree plantations (ca. 11%; Miranda et al. 2015). In this area we can recognise two large landscape types (Rey Benavas et al., 2020): one is composed by relatively small crops with a 117 dense network of reticulate forest which connects small forest patches (hereafter, Landscape A) 118 and other composed by relatively large crop patches (homogeneous monoculture) with a sparse 119 network of reticulate forest and scarce forest patches (hereafter, Landscape B; Figure 1). 120

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## Birds community monitoring

To monitor the bird assemblage, we selected eight roads/tracks (secondary roads, rural ways), inside of our two landscape types, which were suitable to drive on them (without fences or doors), long enough (>10 km) and as straight as possible. Then, we randomly selected four of them for each landscape type (Figure 1). For each transect, we performed 10 count points separated by 1 km between them (n = 80 count points) and located at approx. 50 m away from the road/tracks. To finish the transect on time, before it was too dark, we commuted by car between points. We waited 5 minutes to start the count point after turning off the car. A minimum of two observers participated in every survey. Each week, we recorded one transect for each landscape type between November (2018) and February (2019) (austral spring and summer). In total, we replicated each point 5 times (n = 400 surveys).

The transects started 2 hours before the sunset and each point was observed for 10 minutes 132 (4000 minutes in total). We recorded the bird species present and individuals number observed 133 134 through visual (8 x 42 binoculars) and auditory records within 50 metres of the point. The order of the census points (start and end) was inverted monthly to avoid bias caused by the starting 135 hour. This way, if the order of a transect was from point 1 to point 10 one month, the next month 136 it would be from point 10 to point 1. The transects were always made under the suitable 137 meteorological conditions for a correct visualization, making sure there was no rain or strong 138 139 wind to avoid misidentification (Zuberogoitia et al., 2020). We counted for each point the 140 presence/absence of each bird species. Although usually bird monitoring surveys are made in the 141 sunrise, we choose the sunset because this way could also record some birds with nocturnal 142 habits (e.g., *Tyto alba* and *Asio flammeus*). Some studies show that the peak of detectability of bird species is not related to the sunrise (Gordo et al., 2021) and there are not differences between 143 the hours of the survey (de Araújo et al., 2021). We approach this circumstance into our models 144 using the variable "minutes before the sunset" to model the detection probability. 145

Each bird species was assigned a functional trait based on the main diet of the species (www.avesdechile.cl; Supplementary Material 1). Birds feeding behaviour is fundamental to understand the response of species to environmental changes in the ecosystem (Coelho et al., 2016; Ibarra & Martin, 2015; Luck et al., 2013; Mahoney et al., 2019). Therefore, each species 150 was categorized in the following groups: 1) Granivore; 2) Insectivore; 3) Omnivore; 4)
151 Carnivores/Piscivores, and 5) Herbivores/Frugivores.

#### 152

# Landscape and temporal variables

For each survey point, we delimited a buffer area of 500 meters of radius to identify 153 154 landscape variables (Figure 1). Using Google Earth® imagery (2019) and QGIS software (2004-155 2016), we draw all the habitat types and structures as vectorial shapes and then transformed them into a raster map with a pixel size of 2 meters. We classified the land-use in the following types: 156 1) farmland; 2) tree lines; 3) mixed forest; 4) native forest; 5) wetland; 6) plantation forest; 7) 157 158 river; 8) road; and 9) urban. The native forest was composed mainly by Siempreverde and Roble-Raulí-Coihue forest types (Rey Benayas et al., 2020), where the dominant species are: 159 Nothofagus obliqua, N. dombeyi, Myrceugenia exsucca, Blepharocalyx cruckshanksii, Drimys 160 winteri, Chisquea coleu, Laurelia sempervires, Maytenus boaria and Persea lingue. The mixed 161 forest contains the same typical species of the native forest but also non-native species such as 162 163 Salix babylonica, Eucalyptus globulus, Acacia dealbata, Populus nigra and Ulex europaeus. The plantations are monoculture areas of *Eucalyptus globulus* and *Pinus radiata*. The tree lines are 164 composed by non-native species such as *Populus alba*. Then, we used the software Fragstats 165 166 version 4.2. to calculate the following variables of each land-use cover as measures of landscape structure to be related to biodiversity inside the buffer area: 1) total occupied area (ha); 2) 167 percentage of occupied area; 3) patch density (patches number per each 100 ha); and 4) average 168 patch size (ha) (see Supplementary Material 2). 169

For every survey, we recorded the following variables for each point: 1) Minutes before the sunset (min); 2) Temperature (°C); 3) Rainfall of the previous day (mm); and 4) Wind velocity (km/h) (see Supplementary Material 3). These meteorological data were obtained from two sites (Fundo de Maquehue and El Taplón), which are close (< 5 km) to the transect and belong to 174 "Dirección de Meteorología de Chile (meteochile.gob.cl)" and "Red Agrometeorológica del175 INIA (agromet.inia.cl)", respectively.

176 Data analysis

For our analysis, we considered that our sampling unit is the survey point while the transect 177 178 represents a replica of the landscape. Occupancy models are important to understand the changes 179 in the trends of various species (Pillay et al., 2019; Southwell et al., 2019). Multispecies 180 occupancy models are a more complex framework, aimed at estimating total community richness accounting for differences in species detectability, and few studies have evaluated the effects of 181 182 environmental variables on bird communities (Kéry & Royle, 2008; Kéry & Schmidt, 2008; Zamora-Marín et al., 2021; Zipkin et al., 2009, 2010). We performed a Bayesian multispecies 183 occupancy model, which is an extension of the single species site occupancy model (MacKenzie 184 et al., 2002), whereby the hierarchical structure combines community and species level attributes 185 within a single analytical framework (Zipkin et al., 2009). The hierarchical models are composed 186 187 by the ecological process (governed by occupancy probability) and the observational process (governed by detectability probability). Data are compiled as a  $2x^2$  matrix Y with i rows by k 188 columns, corresponding to count points and species, respectively. The number of spatial 189 190 replicates *i* for each count point *i* where the species *k* was observed is quantified in the matrix *Y*. The ecological process assumes that count point specific occupancy (i.e. "true" 191 presence/absence) for species k = 1, 2, ..., N count point, denoted as z(i, k), where z(i, k) = 1 if 192 species k occurs in count point i and is zero otherwise. 193

The model for occurrence is specified as z(i, k)~*Bernoulli*( $\psi_{i,k}$ ) where ( $\psi_{i,k}$ ) is the probability that species *k* occurs at count point *i*. The true occurrence is imperfectly observed, and we define the detection model for species *k* at count point *i* in replicate *j* as Y(i, k) ~*Binomial* ( $p_{ik} * z(i, k)$ ), where  $p_{ik}$  is the detection probability of species *k* for the *j*<sup>th</sup> spatial replicate at count point *i*, given that species *k* is in fact present at count point *i*, and J(i) is the number of spatial replicates (i.e.,

199 transects) in cell (count point) *i*. We modelled the occurrence probability for species *k* at count point *i* by incorporating site-specific landscape characteristics (Jiménez-Franco et al., 2019; 200 Zipkin et al., 2009). The model included a linear effect of percentage of each forest type (native, 201 202 mixed forest and plantations) in the buffer area and the qualitative variable of landscape type (homogeneous/heterogeneous). We also include effects of functional traits (dietary preferences: 203 granivores, insectivores, omnivores, carnivores/piscivores and herbivores/frugivores) in 204 occupancy probability for species k as a qualitative covariate. All quantitative habitat covariables 205 were standardized by subtracting the mean and dividing by the standard deviation. We assumed 206 that detection probabilities varied depending on the species but were not influenced by the survey 207 characteristics:  $logit(p_k) \sim Normal(\mu_{lp,k}, \sigma^2_{lp,k})$ . We added an additional hierarchical component of 208 the model by assuming that the species-level parameters were random effects, each governed by 209 community-level "hyper-parameters". For example, a community response (mean across 210 species) for a count point and standard deviation (among species) were estimated, so that the 211 hyper-parameters are simply the mean and variance for each covariate, as measured across 212 species (Kéry & Royle, 2016). Model was fitted using JAGS (Plummer, 2003), run in R. 3.6.2 213 (R Core Team, 2016) with the package jagsUI (Kellner, 2015), using uninformative priors, three 214 chains, 15000 iterations and a burn-in of 5000 iterations and a thin rate of 2. 215

We used single season occupancy model to estimate probability of habitat occupancy ( $\psi$ ) at 216 functional trait level (granivores, insectivores, omnivores, carnivores/piscivores, and 217 herbivores/frugivores) while accounting for imperfect detection (MacKenzie et al., 2002). First, 218 we fit a set of detection probability models (*p*). Using the best detection models, we developed 219 220 a set of occupancy probability models for each functional trait. Detection probability and occupancy probability models were fitted according to all possible additive combinations of 221 temporal and landscape variables as covariates, respectively. We also include the type of 222 223 landscape (A or B) as a possible additive or interaction covariate in both modelling processes.

224 We tested the landscape variables of patch density and average patch size for the different forest covers types and isolated trees and the total occupied area for total farmland. Tested covariates 225 did not show a correlation between them (Pearson < 0.6), therefore there cannot be 226 227 multicollinearity in the models. All continuous covariates were standardized before the modelling process to adequately compare the parameters estimated by the models. Models were 228 229 fitted using occu function of the unmarked package in R software (Fiske & Chandler, 2011). Akaike's Information Criterion (AIC) was employed to compare candidate models, and to 230 estimate parameter, unconditional standard errors and 95% confidence via model averaging 231 (Burnham & Anderson, 2002). Model averaging was done using AICcmodavg package in R 232 software (Mazerolle, 2020). Candidate models that represented a 90% confidence set of best-233 ranked regression models were averaged (i.e., models which cumulative Akaike weight  $\leq 0.9$ ; 234 235 Table 1).

Medians of estimated occupancy probabilities using observed landscape variables as 236 predictors were compared between landscape type (A or B) for each functional trait group trough 237 238 Mann-Whitney nonparametric statistical test. We did not use means comparison tests because 239 our data did not present a normal distribution according to Shapiro-Wilk test (p-values equal to 1.66×10<sup>-7</sup>, 9.71×10<sup>-8</sup>, 0.01, 2.02×10<sup>-10</sup> and 2.48×10<sup>-3</sup> for granivores, insectivores, omnivores, 240 carnivores/piscivores and herbivores/frugivores, respectively). Only medians for granivores, 241 insectivores and omnivores were compared, since there was equality of variance between 242 landscape types just for these groups according to Levene's test (p-values equal to 0.36, 0.52, 243  $0.41, 1.59 \times 10^{-3}$  and  $4.70 \times 10^{-5}$  for granivores, insectivores, omnivores, carnivores/piscivores and 244 herbivores/frugivores, respectively). It was not possible to perform a multiple comparison 245 analysis between granivores, insectivores and omnivores, because there was not equality of 246 variance between these groups also according to Levene's test (*p*-value equal to  $1.53 \times 10^{-11}$ ). All 247 statistical tests were performed using a 95% confidence level. 248

249 We used the parametric bootstrap approach to obtain *p*-values from sums of squares, Chisquare and Freeman-Tukey fit statistics that quantified the fit of a model to a data set, and as a 250 measure of the goodness of fit of the worst model used in the model averaging process for each 251 252 functional group (Table 1). We simulated 10,000 bootstrap samples for each fit assessment (Supplementary Material 4). We only evaluated these worst models because the number of totals 253 254 fitted models was very high (due to the large number of possible covariate combinations). If the results suggest that the models provided an adequate fit to the data, then the rest of the models 255 used in the averaging model probably also provided an adequate fit to the data, because they 256 have a better AIC value. A dispersion parameter ( $\hat{c}$ ) was calculated as the ratio of the observed 257 Chi-square fit statistic to the mean of the simulated distribution. 258

259 **Results** 

## 260 *Effects of landscape structure on bird assemblage and species richness*

We recorded a total of 64 bird species in both landscapes (Supplementary Material 1). Our 261 262 models showed that the average number of estimated species per site is  $29.7 \pm 3.5$  (Mean  $\pm$  SD), 263 with values higher than observed  $(20.0 \pm 3.5)$ . The point with fewer species had 12 species, while there were two points with a maximum of 27 species. In landscape A, we recorded 46 species 264 (71.9%) while landscape B had a total of 61 species (95.3%; Supplementary Material 1). 265 Although the landscape B had a higher species number, we did not find differences between both 266 landscape types for the observed species richness ( $19.2 \pm 3.4$  and  $21.6 \pm 3.3$ , landscape A and B 267 268 respectively; W = 534, p < 0.05; Figure 2), but, the estimated species richness was considerably higher in landscape B ( $31.7 \pm 2.7$ ) than landscape A ( $27.3 \pm 2.5$ ; Figure 2). Twelve species were 269 270 only observed in a single point and had a very low naïve occupancy probability (0.012), while the species Vanellus chilensis was observed in 78 out of the 80 points with the highest naïve 271 occupancy probability highest of all the bird assemblage (0.975; see more details in 272 273 Supplementary Material 1).

Our results showed that the bird assemblage had a positive trend with the native forest (Figure 3a), a negative trend with mixed forest (Figure 3b), and a neutral trend for plantations (Figure 3c), where in all the cases the estimated richness in landscape B was higher than in landscape A. The result of multispecies occupancy models for each species-specific showed that occupancy estimates were higher than the detectability estimates for most of the bird species (Supplementary Material 5).

The number of species classified according to their functional trait were the following: 280 granivores (8 species), insectivores (29 species), omnivores (6 species), carnivores/piscivores 281 282 (14 species) and herbivores/frugivores (7 species). The estimated occupancy probabilities were similar for granivores group, however the insectivorous group had a higher probability of 283 occupation in landscape B rather than in landscape A, while the omnivores group had a higher 284 probability in landscape A. The carnivorous/piscivorous group did not show differences between 285 both landscapes while the herbivorous/frugivorous group had a higher occupancy probability in 286 287 landscape A (Figure 4).

#### 288 *Effect of landscape composition and configuration in the bird functional traits*

Bootstrap *p*-values for the worst model used in the model averaging process for each 289 290 functional trait group based on SSE, Chi-square and Freeman-Tukey statistics were 0.46, 0.82, 291 and 0.44 for granivores; 0.42, 0.40 and 0.40 for insectivores; 0.48, 0.40, and 0.44 for omnivores; 0.49, 0.40 and 0.45 for carnivores/piscivores; and 0.48, 0.75 and 0.44 for herbivores/frugivores, 292 293 respectively. These results suggest that the models provided an adequate fit to the data (Supplementary Material 4). The  $\hat{c}$  value were 0.98, 1.00, 1.01, 1.01 and 0.97 for granivores, 294 295 insectivores, omnivores, carnivores/piscivores and herbivores/frugivores, respectively, indicating that there was not under- or over-dispersion. The response of different functional traits 296 for each landscape variable is dependent according to the landscape type analysed. The 297

importance of each variable in the occupancy probability of each functional trait is summarizedin Figure 5.

300 The granivorous group showed a negative response to the mixed forest density in both landscapes (Figure 5 and 6). The insectivores had a positive response for native forest density in 301 landscape B (Figure 5 and 6). The omnivorous group showed a negative response for mixed 302 303 forest and plantation density in both landscapes. However, they showed a positive response for total farmland area (Figure 5 and 6). The carnivores/piscivores only showed significant 304 differences for the native forest average size, where the response is positive (Figure 5 and 6). 305 306 The herbivores/frugivores did not show significant differences for landscape variables (Figure 307 5).

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## Effect of isolated trees on the functional traits

The isolated tree density affected significantly to omnivorous groups (Figure 5), where the omnivores showed a positive response in the landscape B (Figure 6). For the herbivores/frugivores, the average size of isolated tree was negative in landscape A (Figure 6). Nevertheless, the other bird functional traits did not show a significant effect provide by the variables associated with the isolated trees.

314 Discussion

# 315 *Effect of landscape structure in bird assemblage and species richness*

Forest elements are vital to maintain the agroecosystem structure, being the keystone in the conservation and management of the landscape, as well as to develop restoration and rewilding plans (Perino et al., 2019; Rey Benayas et al., 2020). Some studies estimate that it is necessary to get 40% of this structures type to achieve the biodiversity conservation goals (Arroyo-Rodríguez et al., 2020). However, the response of each faunistic group is different to the configuration of these elements and this could have serious implications in the functional traits or species richness. This issue is especially important in agroecosystems, because in the decisionmaking usually, we include the increase of an ecosystem service (e.g., pest suppression) as a promise to persuade the farmers in the need to take wildlife-friendly measures (Cannon et al., 2019; Muñoz-Sáez et al., 2020; Perino et al., 2019). This is especially interesting for birds, a threatened group, highly diversified and which fulfils several roles in the ecosystems.

327 Our results show that in contrast to our initial hypothesis, the landscape with relatively larger crop patches and less reticulate forest had a higher bird species richness compared with the 328 heterogeneous habitats. Moreover, our results showed that the number of observed species was 329 330 quite similar in both landscape types, but the number of estimated species was considerably different. Human activity is probably more intense in landscape A in terms of noise 331 contamination, a factor known to affect the occurrence of numerous bird species (Cooke et al. 332 2020; Sol et al. 2020), especially during the breeding season (León-Ortega et al., 2017). Also, 333 the number of road is higher in this landscape type and the bird assemblage responds negatively 334 335 to this variable (Cooke et al., 2019, 2020), although contrary to other studies we did not find differences in our models. Some endemic Chilean species are sensible to the fragmentation and 336 337 loss of native forest areas (Carvajal et al., 2018). Therefore, it was observed that the 338 homogenization and anthropization process in centre-south Chile affected particularly the specialist species which are less frequent, while the generalist species increased (Ibarra et al., 339 2017; Ibarra & Martin, 2015). Our results show that the native forest density is positive for 340 insectivorous in landscape B but it is negative for omnivorous in landscape A. 341

However, we observed that the forest typologies in La Araucania influence species richness and the occupancy probability of the birds. This way, our results show that the bird species richness had a positive response to the proportion of native forest, a negative response to the mixed forest and a neutral response to plantations. Although the vegetation composition in the mixed forest is native forest alike, the presence of non-native elements (invasive species such as

Ulex europaeus) had a highly negative impact on bird species richness in comparison to the 347 plantations. These invasive species could be detrimental for some bird requirements, such as 348 feeding availability, roosts and breeding areas (Acosta-Rojas et al., 2019). This way, Ibarra et al. 349 350 (2017) found that bird richness is closely associated with native forest and it is lower in the mixed 351 forest. Several studies showed that the presence of Ulex europaeus was associated with the anthropogenic transformation (Altamirano et al., 2016; Cockle et al., 2019; Martín-Gallego et 352 al., 2020), and the bird community is closely linked to forest composition (Adams & Matthews, 353 2019; Ibarra & Martin, 2015). Also, in these areas where there is mixed forest the human activity 354 is high and there are suitable zones for Chilean mesocarnivores (Gálvez et al., 2018; Moreira-355 Arce et al., 2016), which could increase the predation risk of eggs and chicks. Indeed, these 356 357 humanized areas have a great presence of feral cats and dogs (Seymour et al., 2020) and there 358 can also be found invasive birds (Ascensão et al., 2020).

In contrast, the plantations are extensive areas with low human intervention while they are 359 360 not harvested and they are implanted in uninhabited areas. Plantations usually have fences and a restricted access and therefore it is possible that the predator's presence (both natural and exotic) 361 may be low. This way, generalist birds could use these extensive areas to commute between 362 363 habitats (Gardiner et al., 2019). Unlike in Spain, where it was found that there were significant differences between the plantations and native forest on bird species richness (Goded et al., 364 2019), however, our results evidence that mixed forest is worse than plantations. These results 365 366 are related to the ones found in other places, where the functional traits are not related to spatial landscape attributes and therefore, this could affect some ecosystem services such as the pest 367 suppression (Bełcik et al., 2020; Benedetti et al., 2020). 368

369 *Effect of land-use cover and landscape on bird functional traits* 

The configuration and the presence of different landscape elements had a significant impactin occupancy probability of different functional traits (Bełcik et al., 2020). The granivorous

species show a positive relationship with farmland areas, especially in landscape B. This makes sense since the main crops in our study area are allocated by grains production (wheat, oats, rye, etc.). This group is affected negatively by mixed forest (both landscape type) but not by native forest. In landscape B, the native forest size is positive for the granivorous species, however the plantations density had a negative effect.

377 Insectivorous birds were the most abundant group. They showed a negative relationship in landscape B with crops while having a positive one with mixed forest density in landscape A 378 and with native forest density in landscape B. However, the plantations did not have an effect on 379 380 this group. In landscape B, the high native forest density could provide roost and an edge effect where they can perch to hunt their prey (Altamirano et al., 2020; Muñoz-Sáez et al., 2017). Also, 381 these forest elements could help to avoid their predators (Martínez-Núñez et al., 2020). This is 382 especially important if we would like to promote these species for pest suppression in farmland 383 (Muñoz-Sáez et al. 2017, 2020; Martínez-Núñez et al. 2020). 384

Similarly, the omnivorous group had a negative relationship with mixed forest and plantations in both landscapes, also the mixed forest size is negative in landscape B. Since they are a group well adapted to different feeding resources, we found that, in general, the presence of forest habitats (any type) had a negative effect on this group. Probably, the forest areas could increase the predation risk of the omnivorous group. In fact, our models show that the native forest size is positive for carnivores/piscivores.

The increase or maintenance of forest elements not always contribute to the conservation of the intensive grassland/pasture matrix (Bełcik et al., 2020; Duflot et al., 2018; Kameniar et al., 2021). It is necessary to take into account microclimatic changes to understand the specificspecies response (Gaüzère et al., 2020; Threadgill et al., 2020), especially when we measure the functional traits (Klingbeil & Willig, 2016; Redlich et al., 2018).

Lee and Goodale (2018) found that the amount of non-productive vegetation increased the species richness and the occupancy probability in heterogeneous agroecosystems only during winter. Therefore, the transformation in land-uses in the forest of La Araucania could filter the species present today (Lindenmayer et al., 2019).

400 Isolated trees and functional traits

401 In general, none of the functional traits showed any significant effect with the density and/or 402 the size of the isolated trees. Only, the herbivores/frugivores had a negative response in 403 landscape A for the size of the isolated tree and the omnivores showed a positive response in 404 landscape B for the density of isolated tree. Isolated trees can provide resting areas (Altamirano et al., 2017, 2020; Lindenmayer et al., 2019) and suitable micro-habitats for many species (Basile 405 et al., 2020; Cockle et al., 2019). Also, these elements could act as landmarks for various species 406 and help to reduce the "landscape fear" (Gardiner et al., 2019). Our results did not allow us to 407 understand how these landscape elements affect the bird functional traits and probably the 408 409 response type is specific-species.

#### 410 **Conclusions and management implications**

411 In conclusion, our study shows that it is necessary to know how the different elements of landscape architecture affect bird assemblages and functional traits. Our results showed that the 412 mixed forest, which has an important human influence, can be more negative than the 413 414 plantations. Anyway, we observed that the conserved native forest always had a positive effect on species richness and functional traits in La Araucania. Our study evidences that the 415 conservation of native forest is the best policy to maintain the ecosystem services provided by 416 birds such as pest suppression and it is necessary to avoid the entrance of non-native elements 417 (Martín-Gallego et al., 2020). 418

On the other hand, our study is an important contribution to address future restoration plans, because we observed that the maintenance and conservation of the patches of native forest are better and more important than developing a complex reticulated forest. However, we acknowledge the advantages in connectivity that provide the presence of the reticulated forest.

Restoration and rewilding policies must take into account our results and the temporal scales for these landscape changes to avoid possible alterations in the ecosystem services provide by bird functional trait (Gilroy et al., 2014). We found that the presence of forest areas in agroecosystems must be attended to avoid the presence of non-native vegetable species. It is necessary to incorporate social aspects into the conservation and restoration plans for a correct trade-off between the needs of different functional traits in an anthropogenic landscape (Klingbeil & Willig, 2016) to get successful.

The decision-makers should take into account the imperfect detection of species and the hierarchical models that estimate species richness and occupancy accurately to develop win-win strategies (Tarjuelo et al., 2020), as well as to consider the cost and effort of data acquisition, developing survey designs for multi-species techniques (Zipkin et al., 2009).

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439 **Data availability statement** 

440	Data	available	from	Figshare	Digital	Repository:
441	https://figshar	e.com/articles/dat	aset/dataBase	Aves_csv/132689	24	

442 Animal Research (Ethics)

443	No applicable
444	Consent to Participate (Ethics)
445	No applicable
446	Consent to Publish (Ethics)
447	No applicable
448	Plant Reproducibility
449	No applicable
450	Clinical Trials Registration
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802 Table 1: Regression models for functional groups for (A): Detection probability estimation (p) and (B): Occupancy probability estimation ( $\psi$ ). K is number of parameters, AIC is the Akaike's Information Criterion,  $\Delta AIC$  is the difference AIC from the best fit models, AIC.wt is model weight and 803 Cwt is cumulative model weights. Only the best detection model is shown. The best and worst occupancy models represent the extreme models that 804 contain the 90% confidence set of best-ranked (Cwt  $\leq$  0.90). Because the number of occupancy models is too high, only the three best models and 805 the worst are shown based on the AIC value. The worst occupation model of each functional group was used in goodness of fit test (Supplementary 806 Material 4). The landscape variables TOA, PD, APS correspond to total occupied area, patch density (patches number per each 100 ha) and average 807 patch size (ha), respectively. The numbers that accompany the landscape variables indicate the land use type, where 1 = farmland; 3 = mixed forest; 808 4 = native forest; 6 = plantation forest; and 10 = isolated tree. The temporal variables MBS, T, RH, RPD and WV are minutes before the sunset 809 (min), temperature (°C), relative humidity (%), rainfall of the previous day (mm) and wind velocity (km/h), respectively. L is the type of landscape 810 (A or B). 811

Functional Trait	Models	AIC	ΔΑΙΟ	AIC.wt	Cwt
	A. Detection				
	$p(T:L+MBS+L) \sim \psi()$	3662.29			IC.wt         Cwt           0.003         0.003           0.002         0.005           0.002         0.007           0         0.9           0.005         0.005           0.005         0.005           0.005         0.015
	B. Occupancy				
Granivores	$p(T:L+MBS+L) \sim \psi(PD_3)$	3649.52	0	0.003	0.003
	$p(T:L+MBS+L) \sim \psi(PD_3+TOA_1)$	3650.25	0.73	0.002	$\begin{array}{cccc} 03 & 0.003 \\ 02 & 0.005 \\ 02 & 0.007 \\ ) & 0.9 \\ \end{array}$
	$p(T:L+MBS+L) \sim \psi(PD_3+APS+4:L)$	3650.35	0.84	0.002	0.007
	$p(T:L+MBS+L) \sim \psi(PD_3:L+PD_4:L+PD_6:L+APS_4:L+APS_10:L)$	3660.10	10.6	0	0.9
	A. Detection				02 0.005
	$p(\mathbf{L}) \sim \psi()$	6903.50			
	B. Occupancy				
Insectivores	$p(L) \sim \psi(PD_4+L)$	6887.67	0	0.005	0.005
	$p(L) \sim \psi(PD_4+PD_3:L+L)$	6887.79	0.12	0.005	0.01
	$p(L) \sim \psi(PD_4+PD_3:L+TOA_1+L)$	6887.95	0.28	0.005	0.015
	$p(L) \sim \psi(PD\_4+PD\_6:L+PD\_10+APS\_3+APS\_4+APS\_10+TOA\_1:L+L)$	6898.71	11	0	0.9

	A. Detection										
	$p(\text{RPD:L+WV:L}) \sim \psi()$	2164.86			.01       0.01         008       0.012         007       0.024         0       0.9         004       0.004         004       0.009         004       0.013         0       0.9						
	B. Occupancy										
Omnivores	$p(\text{RPD:L+WV:L}) \sim \psi(\text{PD}_3+\text{PD}_6:\text{L+PD}_10+\text{TOA}_1:\text{L+L})$	2131.66	0	0.01	0.01						
	$p(\text{RPD:L} + \text{WV:L}) \sim \psi(\text{PD}_3 + \text{PD}_6 + \text{PD}_10 + \text{TOA}_1:L+L)$	2132.20	0.54	0.008	0.012						
	$p(\text{RPD:L} + \text{WV:L}) \sim \psi(\text{PD}_3 + \text{PD}_6:\text{L} + \text{PD}_10 + \text{APS}_6 + \text{TOA}_1:\text{L} + \text{L})$	2132.54	0.88	0.007	0.024						
	$p(\text{RPD:L} + \text{WV:L}) \sim \psi(\text{PD}_3 + \text{PD}_4 : \text{L} + \text{PD}_6 + \text{PD}_10 : \text{L} + \text{APS}_3 : \text{L} + \text{APS}_4 + \text{APS}_6 + \text{APS}_10 : \text{L} + \text{TOA}_1 + \text{L})$	2142.84	11.2	0	0.9						
	A. Detection										
	$p(\text{RPD+WV}) \sim \psi()$	568.87			0.9 4 0.004 4 0.009 4 0.013						
	B. Occupancy										
Carnivores/Psicivores	$p(\text{RPD+WV}) \sim \psi(\text{PD}_3:\text{L+APS}_4:\text{L})$	561.28	0	0.004	0.004						
	$p(\text{RPD+WV}) \sim \psi(\text{APS}_4:L)$	561.29	0.01	0.004	0.009						
	$p(\text{RPD+WV}) \sim \psi(\text{APS}_4:\text{L+APS}_{10})$	561.38	0.11	0.004	0.013						
	$p(\text{RPD}+WV) \sim$	572.50	11.2	0	0.9						
	$\psi(PD_3:L+PD_4+PD_6:L+PD_10:L+APS_4:L+APS_6+APS_10+TOA_1+L)$	<u>.</u>									
	A. Detection										
	$p(T+WV+L) \sim \psi()$	945.02									
	B. Occupancy										
Herbivores/Frugivores	$p(T+WV+L) \sim \psi(APS_{10}:L+TOA_{1})$	938.10	0	0.002	0.002 0.002						
	$p(T+WV+L) \sim \psi(APS_{10:L+TOA_{1:L+L}})$	938.42	0.32	0.002	0.004						
	$p(T+WV+L) \sim \psi(PD_10:L+TOA_1+L)$	938.43	0.33	0.002	0.006						
	$p(\text{T+WV+L}) \sim \psi(\text{PD}_3 + \text{PD}_6 + \text{PD}_{10:\text{L}} + \text{APS}_4:\text{L} + \text{APS}_6 + \text{APS}_{10} + \text{TOA}_{1+\text{L}})$	948.54	10.4	0	0.9						

814 Figure Captions

815

Figure 1: Example pictures of the spatial heterogeneity in the study area of this project. (A) Large heterogeneity area with relatively small crops, well-connected non-productive elements. (B) Small heterogeneity area with relatively large crops and marginal non-productive elements, dispersed and unconnected. Example raster map with buffer of 500 m radius to calculated the landscape metrics with Fragstats.

821

Figure 2. Boxplots of observed and estimated bird richness associated to the two types of
landscape (A: heterogeneous; B: homogeneous) in La Araucania, Chile. The line inside the box
is the median and the whiskers is the maximum and minimum, respectively.

825

Figure 3. Relationships between the number of bird species (community size, *Nsite*) and the forest type in each landscape type in La Araucaria (Chile): a) native forest (%); b) mixed forest (%); and c) plantations (%). Each point represents the richness of each count point surveyed (n= 80), considering the two types of landscapes in different colour: A, heterogeneous (blue) and

B, homogeneous (green). Lines represent linear splines smooth.

831

Figure 4. Boxplot of estimated occupancy probabilities using observed landscape variables as 832 predictors for each functional trait group according to landscape types (A blue colour or B green 833 colour) resulting of model averaged parameter estimates (across 90% confidence set of best-834 ranked regression models). Mann-Whitney test *p*-values are on top of the upper whiskers of the 835 which indicate statistically significant differences between medians. 836 boxes. For carnivores/piscivores and herbivores/frugivores medians comparison was not made, because 837 there was not equality of variances (Levene's test *p*-values equal to  $2 \times 10^{-3}$  and  $4.7 \times 10^{-5}$ , 838 839 respectively).

840

Figure 5: The importance of each habitat variables in the occupancy probability of each functional group for the two landscapes resulting of model averaged parameter estimates. Bars indicate the 90% confidence intervals. If the bar does not cross the vertical dashed line, this variable is statically significant. Estimates were calculated by averaging across 90% confidence set of best-ranked regression models.

846

Figure 6: Panel plots for each functional traits showing of the occupancy probability in our study area (n = 80) resulting of model-averaged predictions. It only shows the variables which are significant for each landscape type according to the Figure 5. Lines show predicted covariate effects, when all other variables do not influence. Estimates were calculated by averaging across 90% confidence set of best-ranked regression models. Shaded regions are unconditional 90% confidence intervals.





aster map with buffer of 500 radius



860 Figure 3.







# 866 Figure 5:





868 Figure 6:

870 Supplementary Material 1: List of bird species recorded in the two landscape types and their functional traits, as well as observed occupancy and

estimated occupancy (Psi) and detection probability (p) for each bird species. Note that x is equal to the number of sample points in which a

species was detected. Naïve estimate is x divided by 80 (the number of plausible cells within which a species might occur).

Spacing	Codo	Functional traits	Landscape	Landscape	$\mathbf{v}$	Naïve	Estimated	Estimated	Functional
species	Coue	r uncuonar traits	Α	В	Λ	Psi	Psi	р	traits
Agriornis lividus	AGLIV	Insectivore		Х	1	0.01	0.11	0.05	2
Agelasticus thilius	AGTHI	Insectivore	Х	Х	6	0.08	0.71	0.03	2
Anas flavirostris	ANFLA	Insectivore		Х	1	0.01	0.15	0.04	2
Anas georgica	ANGEO	Herbivore/Frugivore	Х	Х	3	0.04	0.51	0.05	5
Anairetes parulus	ANPAR	Insectivore	Х	X	65	0.81	0.92	0.41	2
Anas sibilatrix	ANSIB	Herbivore/Frugivore		Х	1	0.01	0.20	0.07	5
Aphrastura spinicauda	APSPI	Insectivore	Х	Х	25	0.31	0.49	0.29	2
Ardea alba	ARALB	Carnivore/Piscivore	Х	X	7	0.09	0.45	0.19	4
Asio flammeus	ASFLA	Carnivore/Piscivore		Х	2	0.03	0.36	0.07	4
Bubulcus ibis	BUIBI	Insectivore	Х	X	5	0.06	0.30	0.08	2
Carduelis barbata	CABAR	Granivore	Х	Х	36	0.45	0.47	0.18	1
Callipepla californica	CACAL	Granivore	Х	Х	37	0.46	0.28	0.23	1
Cinclodes patagonicus	CIPAT	Insectivore	Х	Х	22	0.28	0.48	0.24	2
Cistothorus platensis	CIPLA	Insectivore		Х	1	0.01	0.02	0.77	2
Columba araucana	COARA	Herbivore/Frugivore	Х	Х	41	0.51	0.94	0.20	5
Coragyps atratus	COATR	Carnivore/Piscivore	Х	Х	15	0.19	0.95	0.06	4
Colaptes pitius	COPIT	Insectivore	Х	Х	40	0.50	0.91	0.17	2
Curaeus curaeus	CUCUR	Omnivore	Х	Х	65	0.81	0.67	0.39	3
Diuca diuca	DIDIU	Granivore	Х	Х	61	0.76	0.44	0.52	1
Elaenia albiceps	ELALB	Omnivore	Х	Х	68	0.85	0.76	0.40	3

Elanus leucurus	ELLEU	Carnivore/Piscivore	Х	Х	10	0.13	0.69	0.12	4
Enicognathus	ENILED	Granivara	$\mathbf{v}$	$\mathbf{v}$	27	0.46	0.19	0.20	1
leptorhynchus	ENLEF	Granivore	Λ	Λ	57	0.40	0.18	0.29	1
Falco femoralis	FAFEM	Carnivore/Piscivore		Х	4	0.05	0.56	0.06	4
Falco sparverius	FASPA	Insectivore	Х	Х	7	0.09	0.29	0.11	2
Fulica armillata	FUARM	Herbivore/Frugivore		Х	1	0.01	0.05	0.78	5
Geranoaetus	GEDOI	Carnivora/Discivora	v	v	Q	0.10	0.87	0.05	1
polyosoma	ULI UL		Λ	Λ	0	0.10	0.87	0.05	4
Hymenops	HVDED	Insectivore	v	v	4	0.05	0.00	0.26	2
perspicillata	HITLK	Insectivore	Λ	Λ	4	0.05	0.09	0.20	2
Leptasthenura	LEVEC	Insectivore	v	v	Q	0.10	0.40	0.08	2
aegithaloides	LEALU	Insectivore	Λ	Λ	0	0.10	0.40	0.08	2
Megaceryle torquata	METOR	Carnivore/Piscivore		Х	2	0.03	0.33	0.07	4
Milvago chimango	MICHI	Insectivore	Х	Х	67	0.84	0.94	0.43	2
Mimus thenca	MITHE	Omnivore	Х	Х	47	0.59	0.17	0.39	3
Molothrus	MORON	Omnivore	v	v	21	0.26	0.46	0.10	3
bonariensis	WODON	Ommvore	Λ	Δ	21	0.20	0.40	0.10	5
Nothoprocta	NOPER	Omnivore	x	x	ΔΔ	0.55	0.44	0.22	3
perdicaria	NOLLK	Ommvore	Λ	Δ		0.55	0.44	0.22	5
Nycticorax nycticorax	NYNYC	Carnivore/Piscivore	Х		1	0.01	0.11	0.05	2
Oxyura ferruginea	OXFER	Carnivore/Piscivore		Х	1	0.01	0.02	0.55	2
Passer domesticus	PADOM	Granivore	Х	Х	20	0.25	0.06	0.37	1
Pardirallus	ΡΔςΔΝ	Insectivore	v	v	Q	0.11	0.83	0.04	2
sanguinolentus	IASAN	Insectivore	Λ	Δ	)	0.11	0.05	0.04	2
Parabuteo unicinctus	PAUNI	Carnivore/Piscivore	Х	Х	6	0.08	0.82	0.04	4
Phalacrocorax	DUBD V	Carnivore/Piscivore	v	v	2	0.03	0.40	0.06	Λ
brasilianus	TIDKA		<b>4</b>	Λ	4	0.05	0.40	0.00	4

Phleocryptes		т.,•		37	1	0.01	0.10	0.05	2
melanops	PHMEL	Insectivore		Х	1	0.01	0.12	0.05	2
Phytotoma rara	PHRAR	Herbivore/Frugivore	Х		24	0.30	0.86	0.16	5
Plegadis chihi	PLCHI	Insectivore		Х	1	0.01	0.14	0.04	2
Porphyriops melanops	POMEL	Herbivore/Frugivore		Х	2	0.03	0.17	0.17	5
Podilymbus podiceps	POPOD	Carnivore/Piscivore	Х	Х	2	0.03	0.14	0.32	4
Pteroptochos tarnii	PTTAR	Insectivore		Х	6	0.08	0.20	0.14	2
Pygarrhichas albogularis	PYALB	Insectivore		Х	16	0.20	0.44	0.15	2
Pygochelidon cyanoleuca	РҮСҮА	Insectivore	Х		2	0.03	0.30	0.04	2
Rollandia rolland	ROROL	Carnivore/Piscivore		Х	1	0.01	0.09	0.31	4
Scytalopus magellanicus	SCMAG	Insectivore	Х	Х	24	0.30	0.47	0.29	2
Scelorchilus rubecola	SCRUB	Insectivore		Х	21	0.26	0.35	0.63	2
Sephanoides sephanoides	SESEP	Herbivore/Frugivore	X	Х	23	0.29	0.75	0.23	5
Sicalis luteola	SILUT	Granivore	Х	Х	76	0.95	0.90	0.52	1
Sturnella loica	STLOI	Omnivore	Х	Х	69	0.86	0.59	0.47	3
Sylviorthorhynchus desmurri	SYDES	Insectivore	Х	Х	16	0.20	0.40	0.21	2
Tachycineta meyeni	TAMEY	Insectivore	Х	Х	54	0.68	0.87	0.31	2
Theristicus melanopis	THMEL	Insectivore	Х	Х	75	0.94	0.97	0.62	2
Troglodytes aedon	TRAED	Insectivore	Х	Х	71	0.89	0.94	0.61	2
Turdus falcklandii	TUFAL	Omnivore	Х	Х	72	0.90	0.96	0.50	2
Tyto alba	TYALB	Carnivore/Piscivore		Х	1	0.01	0.18	0.09	4
Vanellus chilensis	VACHI	Insectivore	Х	Х	78	0.98	0.98	0.86	2

Veniliornis lignarius	VELIG	Insectivore		Х	1	0.01	0.11	0.05	2	
Xolmis pyrope	XOPYR	Insectivore	Х	Х	28	0.35	0.92	0.11	2	
Zenaida auriculate	ZEAUR	Granivore	Х	Х	75	0.94	0.93	0.47	1	
Zonotrichia capensis	ZOCAP	Granivore	Х	Х	77	0.96	0.86	0.76	1	
		Total	46	61						_

Supplementary Material 2: Descriptive statistics of landscape variables. Min, max, SD and CV are the minimum, maximum, standard deviation and coefficient of variation (%), respectively. The variables TOA, POA, PD, APS correspond to total occupied area, percentage of occupied area, patch density (patches number per each 100 ha) and average patch size (ha). The numbers that accompany the variables indicate the land use type, where 1 = farmland; 2 = tree lines; 3 = mixed forest; 4 = native forest; 5 = wetland; 6 = plantation forest; 7 = river; 8 = road; 9 = urban; and 10 = isolatedtree.

		I	Landcap	e A (n = 4)		Landcape B $(n = 40)$						
Variable	Min	Max	Mean	Median	CV %	Min	Max	Mean	Median	SD	CV %	
TOA_1	47.7	72.7	62.5	62.0	6.2	10.0	38.8	77.3	63.1	64.0	7.5	11.9
TOA_2	1.4	6.3	3.5	3.2	1.0	29.7	0.2	6.5	2.7	2.6	1.6	58.5
TOA_3	0.0	10.1	3.2	2.4	2.8	88.0	0.0	24.2	3.5	1.8	4.9	139.6
TOA_4	0.2	20.7	5.8	5.3	4.5	77.5	0.0	17.5	5.3	4.2	4.2	79.1
TOA_5	0.0	0.3	0.0	0.0	0.1	632.5	0.0	2.5	0.1	0.0	0.5	377.1
TOA_6	0.0	11.0	1.1	0.3	2.3	210.6	0.0	24.0	1.8	0.3	4.5	258.1
TOA_7	0.0	6.1	0.5	0.0	1.3	247.8	0.0	4.7	0.4	0.0	1.1	283.6
TOA_8	0.0	2.5	0.9	0.8	0.4	48.0	0.0	1.4	0.9	0.8	0.2	27.4
TOA_9	0.2	2.9	0.8	0.6	0.6	70.1	0.0	1.1	0.3	0.3	0.3	86.4
TOA_10	0.0	1670	321.8	4.9	447.6	139.1	0.17	1558	254.6	0.6	522.3	205.2
POA_1	60.7	92.6	79.7	79.0	7.9	10.0	49.4	98.5	80.4	81.5	9.5	11.9
POA_2	1.8	8.1	4.4	4.1	1.3	29.7	0.2	8.3	3.4	3.3	2.0	58.5
POA_3	0.0	12.9	3.8	2.7	3.5	91.4	0.0	30.9	4.5	2.3	6.2	139.0
POA_4	0.3	26.3	7.1	6.7	5.7	80.3	0.0	22.3	6.8	5.3	5.3	79.1
POA_5	0.0	0.4	0.0	0.0	0.1	632.5	0.0	3.2	0.2	0.0	0.6	377.1
POA_6	0.0	14.0	1.4	0.3	2.9	208.9	0.0	30.5	2.2	0.4	5.8	258.1
POA_7	0.0	7.8	0.7	0.0	1.6	247.8	0.0	6.0	0.5	0.0	1.4	283.6
POA_8	0.0	3.1	1.2	1.0	0.5	45.6	0.5	1.8	1.1	1.1	0.2	21.6
POA_9	0.2	7.1	1.2	0.8	1.2	101.6	0.0	1.4	0.4	0.4	0.3	83.2
POA_10	0.0	0.2	0.1	0.1	0.1	59.3	0.0	0.2	0.1	0.1	0.0	48.5
PD_1	11.5	258.5	73.8	59.2	52.4	71.0	2.6	230.5	54.3	41.4	50.4	92.9
PD 2	42.0	300.6	111.1	86.0	65.7	59.2	10.2	175.8	57.1	43.3	38.8	68.0

PD_3	0.0	15.3	5.6	5.1	3.8	67.8	0.0	19.1	3.3	1.9	4.1	125.6
PD_4	1.3	15.3	4.9	5.1	3.0	60.1	0.0	36.9	5.2	3.8	5.9	113.5
PD_5	0.0	2.6	0.1	0.0	0.5	466.5	0.0	2.6	0.3	0.0	0.7	258.2
PD_6	0.0	14.0	3.1	1.3	3.2	105.8	0.0	6.4	1.2	1.3	1.5	123.8
PD_7	0.0	6.4	0.5	0.0	1.2	263.2	0.0	5.1	0.5	0.0	1.1	255.1
PD_8	0.0	20.4	2.6	1.3	3.9	148.2	1.3	3.8	1.5	1.3	0.6	38.0
PD_9	29.3	214.0	84.5	74.5	44.0	52.1	0.0	177.0	32.2	22.9	35.2	109.3
PD_10	0.0	378.3	87.5	47.1	101.9	116.5	8.9	179.6	57.8	47.1	41.4	71.6
APS_1	0.2	7.7	1.7	1.3	1.5	86.7	0.2	9.7	3.0	2.0	2.7	91.3
APS_2	0.0	0.2	0.1	0.0	0.0	62.5	0.0	0.2	0.1	0.1	0.0	50.5
APS_3	0.0	8.9	0.9	0.5	1.4	163.5	0.0	5.5	1.1	0.7	1.4	128.5
APS_4	0.2	3.8	1.5	1.4	0.9	62.1	0.0	9.7	1.7	1.3	1.7	98.6
APS_5	0.0	0.3	0.0	0.0	0.1	494.4	0.0	1.3	0.1	0.0	0.2	326.4
APS_6	0.0	2.5	0.4	0.2	0.6	144.7	0.0	6.0	0.9	0.2	1.6	186.5
APS_7	0.0	6.1	0.4	0.0	1.2	1.5	0.0	4.7	0.2	0.0	0.8	345.1
APS_8	0.0	1.6	0.7	0.8	0.4	0.1	0.2	1.4	0.8	0.8	0.2	30.0
APS_9	0.0	0.1	0.0	0.0	0.0	0.0	0.0	0.3	0.0	0.0	0.0	209.4
$APS_{10}$	0.0	48.0	16.4	13.0	11.1	122.5	6.0	100.0	22.3	16.5	17.5	78.6

884 Supplementary material 3: Descriptive statistics of temporal variables (n = 400). Min, max, SD 885 and CV are the minimum, maximum, standard deviation and coefficient of variation (%), 886 respectively.

Variable	Min	Max	Mean	Median	SD	CV
Minutes before the sunset (min)	0.0	169.0	73.1	73.0	40.5	55.5
Temperature (°C)	7.5	28.4	18.0	17.7	4.2	23.3
Rainfall of the previous day (mm)	0.0	9.1	0.7	0.0	2.0	267.7
Wind velocity (km/h)	0.2	14.8	7.5	7.8	2.8	37.8

889 Supplementary Material 4: Graphical assessment of model fit by parametric bootstrapping for

890 each functional traits. The dashed line is the observed statistic. The histogram approximates the

891 expected sampling distribution based on 10,000 bootstrap samples for each fit assessment.



893 Supplementary Material 5: Mean of estimates of occupancy probability Psi and detection 894 probability p for bird species in La Araucaria (Chile) considering the different functional traits 895 in colours: omnivores (green); insectivores (red); granivores (black); carnivores/piscivores 896 (blue); herbivores/frugivores (blue light).



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